

Multilevel-Langevin pathwise average for average for Gibbs approximation

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Introduction : Langevin diffusion and Gibbs measure

Let $U : \mathbb{R}^d \rightarrow \mathbb{R}$ be a differentiable function and consider the **SDE** :

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t,$$

where $(B_t)_{t \geq 0}$ is a d -dimensional Brownian motion.

Theorem

Under appropriate assumptions, the solution $(X_t)_{t \geq 0}$ has a unique invariant distribution π with density

$$\pi(x) = \frac{1}{Z_U} \exp(-U(x)),$$

π is called a Gibbs measure.

Objective

The goal is to estimate $\pi(f) := \int_{\mathbb{R}^d} f(x)\pi(dx)$.

Standard Monte Carlo method: *Sample X_1, X_2, \dots, X_N i.i.d with distribution π and define*

$$\mathcal{M}(f) := \frac{1}{N} \sum_{i=1}^N f(X_i).$$

MSE:

$$\|\mathcal{M}(f) - \pi(f)\|_2^2 \leq \frac{\text{Var}(f(X_1))}{N}.$$

Then, $\text{Var}(f(X_1))\varepsilon^{-2}$ ($\approx d\varepsilon^{-2}$ if f is 1-Lipschitz and $\text{Var}(X_1) \leq d$) samples are needed for an ε -approximation.

Multilevel method

Consider a family of random variables $(X_j)_{j \in \mathbb{N}}$ approximating X for J the number of “levels”, observe that

$$\mathbb{E}[X_J] = \underbrace{\mathbb{E}[X_0]}_{\text{coarse}} + \sum_{j=1}^J \underbrace{\mathbb{E}[X_j - X_{j-1}]}_{\text{correcting layer}}.$$

Usually, $X_j := \bar{X}_N^{\gamma_r}$ is an Euler discretization of the **(SDE)** :

$$X_{n+1}^{\gamma_r} = x - \gamma_r \nabla U(X_n^{\gamma_r}) + \sqrt{2\gamma_r} Z_n,$$

where $(Z_n)_{n \in \mathbb{N}}$ is an *i.i.d* sequence of d -dimensional standard Gaussian random variables.

Finite horizon approximation ($\mathbb{E}[f(X_T)]$)

- Giles - 2008 (Multilevel Monte Carlo),
- Lemaire, Pagès - 2014 (Romberg, Multilevel Monte Carlo).

Approximation of the invariant distribution $\pi(f)$

- Pagès, Panloup - 2018 (Ergodic Multilevel, Romberg, decreasing time step).
- Giles, et al. - 2020 (Multilevel Monte carlo),

Ergodic Multilevel : An occupation measure approach

We develop a multilevel procedure using the following property

$$\frac{1}{T} \int_0^T \delta_{X_s} ds \xrightarrow{T \rightarrow +\infty} \pi \quad a.s.$$

Denote by

$$\nu_{\tau, T}^\gamma(f) := \frac{1}{T - \tau} \int_\tau^T f(\overline{X}_s^\gamma) ds,$$

Ergodic Multilevel : the method

Definition

For $J \in \mathbb{N}$ the number of levels, $(T_j)_j$ a decreasing sequence of final time, $(\gamma_j)_j$ a decreasing sequence of time steps. Define the multilevel procedure

$$\mathcal{Y}(f) := \nu_{\tau, T_0}^{\gamma_0}(f) + \sum_{j=1}^J \nu_{\tau, T_j}^{\gamma_j}(f) - \nu_{\tau, T_j}^{\gamma_{j-1}}(f),$$

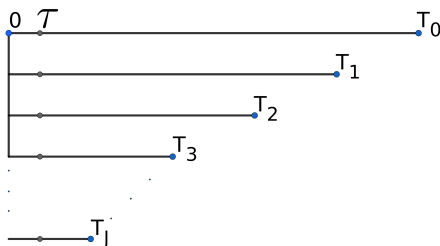
where Euler schemes are **coupled** in each level.

For example,

$\forall j \in \{1, \dots, J\}$:

$$\cdot \gamma_j = \gamma_0 2^{-j}$$

$$\cdot T_j = T_0 2^{-j}$$



Bias-variance decomposition :

$$\begin{aligned}\|\mathcal{Y}(f) - \pi(f)\|_2^2 &= \mathbb{E}[\mathcal{Y}(f) - \pi(f)]^2 + \text{Var}(\mathcal{Y}(f)) \\ &\leq 2 \underbrace{|\pi^{\gamma_J}(f) - \pi(f)|^2}_{\text{discretization error}} + 2 \underbrace{\mathbb{E}[|\mathcal{Y}(f) - \pi^{\gamma_J}(f)|^2]}_{\text{longtime error}} + \text{Var}(\mathcal{Y}(f)),\end{aligned}$$

Hypothesis

H_1 (Convergence to equilibrium) : There exist $\alpha > 0$ and $c_1 > 0$ such that for all $t \geq 0$,

$$|\mathbb{E}[f(X_t)] - \pi(f)| \leq c_1 e^{-\alpha t}. \quad (1)$$

H_2 (weak error) : There exists $c_2 > 0$ such that for all $\gamma \in (0, \eta_0]$,

$$|\pi(f) - \pi^\gamma(f)| \leq c_2 \gamma^\delta, \quad (2)$$

where δ is a positive number.

H_3 (L^2 confluence) : There exist $\rho \geq 1$ and a real constant c_3 such that for every $t \geq 0$,

$$\sup_{t \geq 0} \left\| \overline{X}_t^{\gamma/2} - \overline{X}_t^\gamma \right\|_2 \leq c_3 \gamma^{\frac{\rho}{2}}. \quad (3)$$

H_4 (control of the moments) : There exists a constant $c_4 > 0$ such that for all $\gamma \in (0, \eta_0]$,

$$\sup_{t > 0} \left\| \overline{X}_t^\gamma \right\|_2 \leq c_4. \quad (4)$$

Ergodic Multilevel

Theorem

Assume H_1, H_2, H_3 and H_4 and ∇U is L -Lipschitz continuous. Let f be a Lipschitz continuous function. Then, for any $\varepsilon > 0$, there exist parameters such that

$$\|\mathcal{Y}(f) - \pi(f)\|_2 \leq C\varepsilon,$$

where C is a constant depending on c_1, c_2, c_3 and c_4 . Furthermore, the complexity is

$$\text{Compl}(\mathcal{Y}) \simeq \begin{cases} \varepsilon^{-2} \log(\varepsilon^{-1})^3 & \text{if } \rho = 1, \\ \varepsilon^{-2} & \text{if } \rho > 1. \end{cases} \quad (5)$$

Ergodic Multilevel : Complexity

For example :

$$\tau = \frac{1}{\alpha} |\log(\varepsilon)|, \quad J = \left\lceil \frac{|\log(\varepsilon)|}{\log(2)} \right\rceil, \quad \gamma_j = \gamma_0 2^{-j},$$

$$T_j = \begin{cases} 2^{-j} \varepsilon^{-2} |\log(\varepsilon)|^2 & \text{if } \rho = 1, \\ 2^{-j \frac{\rho+1}{2}} \varepsilon^{-2} & \text{if } \rho > 1, \end{cases}$$

The complexity cost of the method is given by

$$\text{Compl}(\mathcal{Y}) = \frac{T_0}{\gamma_0} + \sum_{j=1}^J \frac{T_j}{\gamma_j} + \frac{T_j}{\gamma_{j-1}}.$$

What is the dependence on the dimension of the complexity ?

Application to uniformly convex setting

C_s : There exists $\alpha > 0$ such that for all $x, y \in \mathbb{R}^d$,

$$\langle \nabla U(x) - \nabla U(y), y - x \rangle \leq -\alpha |x - y|^2.$$

Proposition

Assume C_s and ∇U is L -Lipschitz continuous. Let $\gamma_0 \in (0, \frac{\alpha}{2L^2}]$. Then H_1 , H_2 , H_3 and H_4 hold with $\rho = 1$,

$$c_1(x) \leq C(|x| + \sqrt{d}) \quad \text{and} \quad c_i \leq C\sqrt{d} \quad \text{for } i \in \{2, 3, 4\},$$

where C does only depend on L and α .

Application to uniformly convex setting

Corollary

Assume C_s , ∇U is L -Lipschitz continuous and f is 1-Lipschitz continuous. Then for any $\varepsilon > 0$ there exist parameters such that $\mathcal{Y}(f)$ is an ε -approximation of $\pi(f)$ and

$$\text{Compl}(\mathcal{Y}) \leq d\varepsilon^{-2} \frac{CL^2}{\alpha^3},$$

where C is a universal constant.

Merci pour votre attention !



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