

On convergence of stochastic Mayer problems with transaction cost

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Basic model in discrete time

Values versus physical units

There are d assets which we prefer to interpret as currencies. Their **quotes** are given in units of a certain *numéraire* which may not be a traded security. At time t the quotes are expressed by the vector of prices $S_t = (S_t^1, \dots, S_t^d)$; its components are **strictly positive**. We assume that $S_0 = \mathbf{1} = (1, \dots, 1)$.

The agent's positions can be described either by the vector of **"physical" quantities** $\widehat{V}_t = (\widehat{V}_t^1, \dots, \widehat{V}_t^d)$ or by the vector $V = (V_t^1, \dots, V_t^d)$ of **values** invested in each asset; they are related as follows :

$$\widehat{V}_t^i = V_t^i / S_t^i, \quad i \leq d.$$

Formally, $\widehat{V}_t = \varphi_t V_t$, where

$$\varphi_t : (x^1, \dots, x^d) \mapsto (x^1 / S_t^1, \dots, x^d / S_t^d).$$

Basic model in discrete time

Dynamics

The portfolio evolution can be described by the initial condition $V_{-0} = v$ (the endowments of the agent when entering the market) and the increments at dates $t \geq 0$:

$$\Delta V_t^i = \widehat{V}_{t-1}^i \Delta S_t^i + \Delta B_t^i,$$

$$B_t^i := \sum_{j=1}^d L_t^{ji} - \sum_{j=1}^d (1 + \lambda_t^{ij}) L_t^{ij},$$

where $L_t^{ji} \in L^0(\mathbf{R}_+, \mathcal{F}_t)$ represents the accumulated net amount transferred from the position j to the position i at the date t ; (ΔL_t^{ij}) , interpreted as an “order” matrix, is a control; (λ_t^{ij}) is the matrix of **transaction costs coefficients** : $\lambda_t^{ij} \in L^0(\mathbf{R}_+, \mathcal{F}_t)$, $\lambda^{ii} = 0$.

Dynamics in terms of numéraire

The portfolio dynamics can be described by a controlled linear difference equation :

$$\Delta V_t^i = V_{t-1}^i \Delta Y_t^i + \Delta B_t^i, \quad i = 1, \dots, d,$$

where Y^i , a “stochastic logarithm” of S^i , is given by follows :

$$\Delta Y_t^i = \frac{\Delta S_t^i}{S_{t-1}^i}, \quad Y_0^i = 1.$$

We can take ΔB_t as the control. Any $\Delta L_t \in L^0(\mathbf{M}_+^d, \mathcal{F}_t)$ defines $\Delta B_t \in L^0(-K_t, \mathcal{F}_t)$ where K_t is the solvency cone

$$K_t := \left\{ x \in \mathbf{R}^d : \exists a \in \mathbf{M}_+^d \text{ such that } x^i \geq \sum_j [(1 + \lambda_t^{ij}) a^{ij} - a^{ij}] \right\}.$$

A measurable selection arguments show that any increment $\Delta B_t \in L^0(-K_t, \mathcal{F}_t)$ is generated by a certain (in general, not unique) order $\Delta L_t \in L^0(\mathbf{M}_+^d, \mathcal{F}_t)$.

Dynamics in physical units and the Cauchy formula

- The portfolio dynamics in physical units is surprisingly simple and, financially, obvious :

$$\Delta \widehat{V}_t^i = \frac{\Delta B_t^i}{S_t^i}, \quad i = 1, \dots, d.$$

- We can write this as :

$$\Delta \widehat{V}_t = \widehat{\Delta B}_t, \quad -\widehat{\Delta B}_t \in \widehat{K}_t := \varphi_t M_t.$$

- It follows that

$$V_t^i = S_t^i \widehat{V}_t^i = S_t^i \left(v^i + \sum_{s=0}^t \frac{\Delta B_s^i}{S_s^i} \right).$$

This is just the Cauchy formula for the solution of the non-homogeneous linear difference equation.

Problem formulation

We are given

- a closed proper convex cone $K \subset \mathbb{R}^d$ such that $\text{int } K \supset \mathbb{R}_+^d \setminus \{0\}$,
- a probability measure μ on the space C^d of continuous functions x on $[0, T]$ with values in $]0, \infty[^d$ and such that $x_0 = \mathbf{1} = (1, \dots, 1)$ and $x_t^1 \equiv 1$,
- a function $U : K \times C_{++}^d[0, T] \rightarrow \mathbb{R}_+$ such that for each f the function $v \mapsto U(v, f)$ is concave and increasing with respect to the componentwise partial ordering in \mathbb{R}^d (i.e., induced by the cone \mathbb{R}_+^d).

In our terminology *model* $\mathbf{M}(\mu)$ is a stochastic basis

$\mathbb{B} = (\Omega, \mathcal{F}, \mathbf{F} = (\mathcal{F}_t)_{t \in [0, T]}, \mathbf{P})$ satisfying the usual conditions on which is defined a process S having the law μ and such that its natural filtration $\mathbf{F}^S = \mathbf{F}$.

Fix a model $\mathbf{M} = \mathbf{M}(\mu)$.

We associate with K and S the cone-valued processes $\widehat{K}_t := K/S_t$ and \widehat{K}_t^* . In a formal way $\widehat{K}_t := \varphi_t K$, where $\varphi_t : (x^1, \dots, x^d) \mapsto (x^1/S_t^1, \dots, x^d/S_t^d)$. Then $\widehat{K}_t^* = \varphi^{-1} K^*$.

Let $B = (B_t)_{t \leq T}$ be an \mathbb{R}^d -valued adapted càdlàg process of bounded variation, $\text{Var } B = \text{Var}_t B$ be the sum of $\text{Var } B^i$, and $\dot{B}_t := dB_t/d\text{Var}_t B$ is an optional process. If $\dot{B}_t \in -K$ the process B is called *control* or *strategy*.

For a control B and $x \in K$ the processes $\widehat{V} = \widehat{V}^{x,B}$ has the components $\widehat{V}^i := x^i + (1/S^i) \cdot B^i$ and $V = \varphi^{-1} \widehat{V}$ with $V^i = S^i \widehat{V}^i = S^i(x^i + (1/S^i) \cdot B^i)$.

If S is a semimartingale, the product formula implies that $V^i = x^i + V^i \cdot L^i + B^i$ where $L^i := 1 + (1/S^i) \cdot S^i$. Alternatively, $V^i = x^i + \widehat{V}^i \cdot S^i + B^i$.

The convex set $\mathcal{A}(x) = \mathcal{A}(x, \mathbf{M})$ of *admissible strategies* is formed by the controls B such that $\widehat{V}^{x,B} \in \widehat{K}$, i.e., $\widehat{V}_t^{x,B} \in \widehat{K}_t$, $t \in [0, T]$. Clearly, $\mathcal{A}(y) \supseteq \mathcal{A}(x)$ if $y - x \in K$, $\mathcal{A}(\lambda x) = \lambda \mathcal{A}(x) \forall \lambda > 0$.

The Mayer problem and its stability

The aim of the control is to minimize over $\mathcal{A}(x, \mathbf{M})$ the expected utility $\mathbf{E}[U(\widehat{V}_T^{x,B}, S)]$, i.e. to find the Bellman function for the model $\mathbf{M} = \mathbf{M}(\mu)$

$$u(x, \mathbf{M}) := \sup_{B \in \mathcal{A}(x, \mathbf{M})} \mathbf{E}[U(\widehat{V}_T^{x,B}, S)]. \quad (1)$$

Let $\mathbf{M}^n := \mathbf{M}(\mu^n)$ where μ^n to μ weakly.

The question is whether $u(x, \mathbf{M}^n)$ converges to $u(x, \mathbf{M})$?

Assumption A.1. There are two continuous functions $m_i : [0, 1] \rightarrow \mathbb{R}_+$ with $m_i(0) = 0$, $i = 1, 2$, and an integrable random variable $\zeta \geq 0$ such that for all $x \in K$ and $\alpha > 0$

$$U((1 - \alpha)x, S) \geq (1 - m_1(\alpha))U(x, S) - m_2(\alpha)\zeta. \quad (2)$$

Lemma

*Suppose that **A.1** holds. Then u is continuous on $\text{int } K$.*

Approximations of strategies

Lemma

Let $\varepsilon \in]0, 1]$ be such that $\mathcal{O}_\varepsilon(x) \subset \text{int } K$. Let $B \in \mathcal{A}(x)$ and let B^m be the strategy defined as follows :

$$B^m := b_0 I_{[t_0, t_1[} + \sum_{k=1}^{m-1} (B_{t_k} - B_{t_{k-1}}) I_{\Delta_k} + B_T I_{\{T\}}, \quad \Delta_k := [t_k, t_{k+1}[, \quad t_k =$$

Then

(i) $|\widehat{V}_T^{x, B^m} - \widehat{V}_T^{x, B}| \rightarrow 0$ as $m \rightarrow \infty$;

(ii) there is an \mathbb{R}^d -valued adapted càdlàg process

$\xi^m = \xi^m(x, S, B)$ with jumps only at the points t_k and such that $\|\xi^m\| \rightarrow 0$ as $m \rightarrow \infty$ and

$$\widehat{V}_t^{x, B^m} + \xi_t^m \in \widehat{K}_t \quad \text{for all } t \in [0, T].$$

Lemma

Let $\delta > 0$, $l\zeta$ be an \mathbb{R}^k -valued r.v., and η be a $\sigma\{\zeta\}$ -measurable r.v. with values in a closed convex cone G . Then there is a bounded continuous function $f : \mathbb{R}^k \rightarrow G$ such that $\mathbf{E}[|f(\zeta) - \eta| \wedge 1] < \delta$.

Lemma

Let $\delta > 0$ and let η be a G -valued \mathcal{F}_t -measurable r.v. . Then there are $r_i \in [0, t]$, $i = 1, \dots, M$, and a bounded continuous function $f : (\mathbb{R}^p)^M \rightarrow G$ such that $\mathbf{E}[|f(Y_{r_1}, \dots, Y_{r_M}) - \eta| \wedge 1] < \delta$.

Lemma

Let $\mathcal{B}_m(\mathbf{F})$ be the set of \mathbf{F} -adapted processes constant on each $[t_k, t_{k+1}[$ with $\Delta B_{t_k}^m \in L^0(-K, \mathcal{F}_{t_k})$. Let $\mathcal{B}_m^c(\mathbf{F})$ be its subset consisting of the processes such that $\Delta B_{t_k}^m$ are bounded continuous functions of values of the process Y at a finite subset of $[0, t_k]$. Then for any $B^m \in \mathcal{B}_m(\mathbf{F})$ there are $B^{m,l} \in \mathcal{B}_m^c(\mathbf{F})$ with $\|B^{m,l} - B^m\| \rightarrow 0$ a.s. as $l \rightarrow \infty$.

Assumption A.2. The value function of the problem does not depend on the model : $u(x, \mathbf{M}^n) =: u^n(x)$, $u(x, \mathbf{M}) =: u(x)$.

Proposition

*Suppose that **A.1** and **A.2** hold. Let $x \in \text{int } K$. Then*

$$u(x) \leq \liminf_n u^n(x).$$

Assumption A.3. There exist a cone K' and cones K'^n , satisfying the following property : $K' \subset \text{int} K' \cup \{0\}$ and $K'^n \subset \text{int} K'^n \cup \{0\}$. There also exist probability measures $\mathbf{Q} \sim \mathbf{P}$, $\mathbf{Q}^n \sim \mathbf{P}^n$, $n \in \mathbb{N}$ and local \mathbf{Q}^n -martingales M_t^n with a local \mathbf{Q} -martingale M such that

$$|M_t - S_t| \in K'^*, \quad \mathbf{P}\text{-a.s.} \quad \forall t \in [0, T], \quad (3)$$

$$|M_t^n - S_t^n| \in K_n'^*, \quad \mathbf{P}^n\text{-a.s.} \quad \forall n \in \mathbb{N} \quad \forall t \in [0, T]. \quad (4)$$

Assumption A.4. The sequence of probability measures \mathbf{P}^n is contiguous with respect to the sequence \mathbf{Q}^n , where \mathbf{Q}^n is taken from the previous assumption.

Theorem

Under A.1-A.4 $u^n(x) \rightarrow u(x)$.



Bayraktar, E., Dolinsky, L., Dolinsky, Y. : Extended weak convergence and utility maximisation with proportional transaction costs. *Finance and Stochastics*, **24**, 4, 1013–1034 (2020)